Abundance and demographic parameters of bottlenose dolphins in a highly affected coastal

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- 10 **Abstract.** This study presents the first robust estimates of abundance and demographic parameters of common
- bottlenose dolphins (*Tursiops truncatus*) in a highly affected coastal ecosystem along the north-eastern Atlantic.
- 12 Seasonal abundance, apparent survival and temporary emigration rates were estimated using Pollock's robust
- design models. Photographic identification data were collected from 2014 to 2016 along the north-western Iberian
- coast (Spain). Bottlenose dolphins were present year-round and with a high degree of occurrence in the study area,
- 15 which is highly affected by human activity but is also a highly productive coastal ecosystem. Local abundance of
- bottlenose dolphins ranged from 56 in autumn 2014 to 144 in winter 2015. Apparent survival rate was high and
- 17 constant, indicating no mortality and no permanent emigration. Temporal emigration rates varied seasonally and
- were lower from autumn to winter, suggesting that dolphins had a high probability of returning during the winter
- 19 period. The observed changes in abundance and emigration rates most likely reflect seasonal fluctuations in
- abundance of prey species in this area. These results provide important baseline information in an area subject to
- 21 significant anthropogenic pressures and for future comparisons with other populations of similar characteristics
- 22 under the pressure of human activities, such as fisheries and aquaculture.
- 24 Additional keywords: anthropogenic disturbances, Iberian Peninsula, marine top predator, photographic
- 25 identification.

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- Worldwide, coastal and marine ecosystems are at risk as a result of human activities (Halpern et al.
- 30 2008). Consequently, cetacean species that live near shore are highly vulnerable to a variety of
- anthropogenic pressures, such as fisheries (Read et al. 2006), aquaculture (Würsig and Gailey 2002;
- 32 Díaz López 2012), pollution (Derraik 2002; Tanabe 2002), global warming (Simmonds and Isaac 2007)
- and habitat modification (Lotze et al. 2006). Estimating demographic parameters of a cetacean

population is crucial for assessing their conservation status and to identify potential effects of anthropogenic or natural pressures in order to take appropriate conservation and management measurements (Smith et al. 2013).

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Having a near shore distribution, the common bottlenose dolphin Tursiops truncatus (Montagu 1821), hereafter 'bottlenose dolphin', is among the most threatened cetacean species, and a more intense monitoring and management intervention is needed for this species (Bearzi et al. 2009). Atlantic bottlenose dolphin populations are listed in Appendix II of the Convention on the Conservation of Migratory Species of Wild Animals (CMS; www.cms.int 15 October 2017), in Appendix II (Strictly Protected Fauna Species) of the Convention on the Conservation of European Wildlife and Natural Habitats (Bern Convention; www.coe.int 15 October 2017) and under Annexes II and IV of the European Union's Habitats Directive (Council Directive 92/43/EEC; www.ec.europa.eu 15 October 2017) as a species whose conservation requires the designation of Special Areas of Conservation and in need of strict protection.

In order to obtain accurate and precise information about bottlenose dolphin populations, year-round survey efforts are essential, but these are expensive and logistically challenging (i.e. weather conditions, limited resources and personnel). In north-east Atlantic waters, although some studies have focused on local abundance (Silva et al. 2009; Berrow et al. 2012; Hammond et al. 2013), there is a lack of exhaustive robust assessments of population abundance, rates of apparent survival and temporary emigration of bottlenose dolphin populations.

Bottlenose dolphins are present along the north-western Iberian coast (López et al. 2003; Pierce et al. 2010; Louis et al. 2014; Díaz López and Methion 2017), a region where they are vulnerable to several human impacts that affect coastal areas throughout the Atlantic coastline, such as marine traffic, bycatch (López et al. 2003), overfishing (Freire and García-Allut 2000), oil spills (Vieites et al. 2004) and the aquaculture industry (Díaz López and Methion 2017). A recent study demonstrated that bottlenose dolphins present a fine-scale pattern of habitat selection affected by anthropogenic activities in these waters (Díaz López and Methion 2017). However, the lack of exhaustive robust assessments of population abundance and demographic parameters hampers our ability to evaluate the effects of human activities on this species in the region.

Over the past few years, Pollock's capture-recapture robust study design (Pollock 1982) has been increasingly used to obtain accurate estimates of abundance and other demographic variables of bottlenose dolphin populations (e.g. Silva et al. 2009; Speakman et al. 2010; Nicholson et al. 2012; Bassos-Hull et al. 2013; Smith et al. 2013; Fruet et al. 2015; Santostasi et al. 2016; Sprogis et al. 2016). This design, unlike standard open models, takes into account the degree of residency, including temporary emigration, thus more accurately reflecting reality in the results (Kendall et al. 1997; Nicholson et al. 2012; Smith et al. 2013). Indeed, temporary or permanent emigration can potentially

be confounded with mortality, and may result in imprecise, and in some circumstances biased, estimations (Kendall *et al.* 1997). By using Pollock's robust design model it is possible to control the effects of temporary emigration on the population, thus making the model less sensitive to the observed violations of 'equal catchability' when the recapture period is extended over time (Pollock 1982). Pollock's robust design combines open population models (open sampling event; termed 'primary periods') and closed population models (multiple closed events within the open sampling event; termed 'secondary periods'; Kendall *et al.* 1997). Although the population is assumed to be open between primary periods (i.e. allowing for births, deaths and permanent or temporary emigration and immigration), each secondary period assumes an effectively closed unit (i.e. births, deaths, immigration and emigration do not occur; Kendall *et al.* 1997).

In the present study, we used Pollock's robust design models on photographic identification data collected year-round to estimate seasonal abundance, apparent survival and temporary emigration rates of common bottlenose dolphins along the north-western Iberian coast (Spain). These estimates are the first robust estimates for a coastal bottlenose dolphins in north-eastern Atlantic waters and provide important baseline information in an area subject to significant anthropogenic pressures.

Materials and methods

Study area

The present study was performed along the north-western coast of the Iberian Peninsula, specifically along the southern coast of Galicia (Spain), on which there are a series of ancient drowned tectonic valleys taken over by the sea (also referred to as 'rías'; Evans and Prego 2003). Owing to intense upwelling events that occur along this coast, resulting in very high primary production, the rías are important areas for fisheries and shellfish aquaculture, and more specifically for the production of mussels and oysters (Prego *et al.* 1999). Rías are often sites for human settlement, where many pollution problems exist, because they serve as harbours and waterways to urban and industrial centres (Prego and Cobelo-García 2003).

Boat-based surveys were conducted in the coastal waters of the largest of the Galician rías, the Ría de Arousa (Prego *et al.* 1999), and surrounding waters up to 20 km offshore, covering an area of 450 km² with a maximum depth of 150 m. The average depth of the Ría de Arousa is 19 m. The entire system is subjected to a semidiurnal and mesotidal tide regime, with a tidal range of 1.1 and 3.5 m during neap and spring tides respectively (Alvarez *et al.* 2005). During the study, the sea surface water temperature ranged between 9°C in winter and 22°C in summer.

Data collection

Boat-based surveys were conducted in the study area between March 2014 and June 2016 using a 12-m research vessel powered by two 180-hp inboard engines. Because of poor weather conditions

during December we were unable to complete surveys during this month. In all, 25 months were spent in the field.

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The area was surveyed during daylight hours at a constant speed of 6 kn with at least three experienced observers stationed on the flying bridge (4 m above sea level) scanning 360° of the sea surface in search of common bottlenose dolphins (*T. truncatus*) with the naked eye or 10×50 binoculars. The minimum number of experienced observers and vessel speed remained consistent during the study period, making data suitable for comparative analysis. Boat-based observations were performed when the visibility was not reduced by rain or fog, and sea conditions were <3 on the Douglas sea force scale (Díaz López 2006). The survey area and track were designed to attempt to equally cover all parts of the study area, although the geographic distribution of effort could vary according to weather conditions (Díaz López and Methion 2017).

Upon encountering a group of bottlenose dolphins, searching effort ceased and the vessel slowly manoeuvred towards the group in order to minimise disturbance during approach. A group of dolphins was defined as either a solitary dolphin or any aggregation of bottlenose dolphins with close spatial cohesion, with interactions between individuals and participating in the same behavioural activities. The date, initial and final time, location (Universal Transverse Mercator (UTM) coordinates) and group size and composition were recorded for each encounter. Attempts were made to photograph both sides of the dorsal fin of every dolphin present in the group, regardless of the degree of marking, age class or behaviour. Photographs were taken using digital single lens reflex (SLR) cameras equipped with a 35to 300-mm telephoto zoom lens. Group size was assessed based on the initial count of different individuals observed at one time in the area. Field data were later verified with photographs taken during each encounter by increasing the number of individuals present if more individuals were photographed (Díaz López and Shirai 2008). Individual dolphins were classified according to age within each group at the time of the encounter (Scott et al. 1990). Age class definitions followed those of Díaz López and Methion (2017), whereby bottlenose dolphins were classified as either newborn, immature or adult. Newborn dolphins were defined as dependent dolphins <1.5 m with fetal folds or lines. Newborns were also defined on the basis of uncoordinated surfacing behaviour and swimming in the infant position (i.e. below the mother, lightly touching her abdomen). Immature dolphins were those with few rake marks and skin lesions and two-thirds or less the length of adults. Immature dolphins were often observed in close association with an adult, but never observed in the infant position. Adult dolphins were fully grown (length >2.5 m) marked or unmarked animals with darker skin colouration. Sex was determined by direct observations and photographs of the genital region, as described by Díaz López (2012). The sex of male bottlenose dolphins was determined by the observation of an erection, by the gap (>2.5 cm) between the genital and anal slits and a lack of mammary slits, or by the gap alone. Females were sexed by the observation of mammary slits or the consistent presence of a newborn swimming in the infant

- position. After the end of an encounter, the search effort generally continued along the previously
- 139 planned route.
- Data collection in the present study complied with current laws of Spain, the country in which the
- study was performed.
- 142 Relative frequency of occurrence
- In order to understand the temporal pattern in the presence of groups of bottlenose dolphins in the
- study area, a relative frequency of occurrence (hereafter referred to as the encounter ratio (ER); Díaz
- López 2006) was computed as follows:

$$146 \qquad ER = \frac{Ne}{h}$$

- where Ne is the total number of encounters and h is the total number of hours spent searching for
- dolphins.
- Non-parametric tests (Mann–Whitney or Kruskal-Wallis) were used to investigate the equality of
- medians of quantitative samples. Statistical significance was tested at the P < 0.05 level. The data are
- presented as means \pm standard error (s.e.).
- 152 Analysis of photographs
- All digital photographs were analysed independently by three experienced researchers. Only adult
- bottlenose dolphins were included in the photographic identification analysis; therefore, photographs
- 155 containing calves (immature and newborn dolphins) were excluded. Adult bottlenose dolphins were
- identified from photographs based on the size, location and pattern of notches on the trailing edge of
- the dorsal fin (Würsig and Jefferson 1990). All photographs containing a dorsal fin were graded for
- quality and degree of distinctiveness in order to minimise misidentification and heterogeneity in capture
- probabilities (Urian et al. 2015). Following Díaz López et al. (2017), all photographs were given an
- absolute value score (1 = low; 4 = average; 10 = high) for: (1) the perpendicular angle of the dorsal fin
- to the camera; (2) the focus of the image being sufficient to allow all notches to be distinguished; (3)
- 162 contrast and light intensity; and (4) the dorsal fin being suitably sized in the frame for all notches to be
- clearly visible. The individual scores for each category were summed to obtain an overall quality score
- 164 (OQS). OQSs from 4 to 16 were considered poor quality; those from 19 to 25 were considered to be of
- 7. 6.7
- average quality and those ≥28 were considered excellent. To ensure correct identification of individuals,
- only excellent quality photographs were used for individual identification. In addition, each adult
- individual was included in a distinctiveness category, based on the amount of information contained on
- the dorsal fin, to ensure that more distinctly marked individuals would not have a higher probability of
- being identified. A 'well-marked individual' was considered to be a dolphin that is recognised not by a
- single large feature in the dorsal fin, but also by a matrix of evident notches (Würsig and Jefferson

1990). A 'marked individual' was considered to be a dolphin with a distinct dorsal fin with an average amount of information (i.e. a single large notch and several small notches). Features such as body and dorsal fin scars, lesions, decolouration and tooth rakings were used as secondary characteristics, thereby reducing the possibility of false positives (Wilson *et al.* 1999). A 'poorly marked individual' was considered to be a dolphin with a dorsal fin that had a small amount of information (i.e. a small notch and secondary characteristics). Because such characteristics are not necessarily permanent and not easily identifiable, adult individuals with no marks on the dorsal fin (unmarked) and poorly marked individuals were not included in further analyses.

Every photograph of identified individuals was re-examined for false positives (different dolphins being assigned as the same individual) and false negatives (the same dolphin being assigned as multiple discrete individuals), and the final data were confirmed by two experienced observers. Later, to avoid potential errors because of observer fatigue during the photographic identification analysis, the matching of the individuals was confirmed using DARWIN 2.22 (Hale 2008). The best photographs of both sides of every adult bottlenose dolphin were kept in an identification catalogue. Photographs were regularly replaced in the catalogue as better-quality or more current images became available. The capture history (whether or not an identified bottlenose dolphin was present within a sampling period) for each individual was compiled after the photographic grading process.

Mark-recapture abundance models

In the present study we used Pollock's robust design model to estimate abundance and survival rates (Pollock 1982; Kendall *et al.* 1997) of the bottlenose dolphins studied. Primary periods were based on each season of the year: winter (January–March), spring (April–June), summer (July–September) and autumn (October–December). Secondary periods were based on the minimum number of photographic identification surveys necessary to monitor the entire study area and were completed within the shortest time possible (weather dependent; Smith *et al.* 2013). Nine primary periods (seasons of the year) and 22 secondary periods were included in the robust design models. There were two or three secondary periods within each primary period. The time taken to complete secondary periods was weather dependent and averaged 23 ± 2 days (range 7–40 days) because of logistical reasons and weather conditions.

Model assumptions

- Several assumptions need to be satisfied in order to obtain unbiased estimates with robust capture recapture models, as detailed below.
- 1. Marks are unique, they cannot disappear and there are no misidentifications. To ensure this assumption, unique and evident nicks were used to identify 'well-marked' and 'marked' adult bottlenose dolphins, and digital photographs were double-checked by experienced researchers and posteriorly confirmed using matching software. Although marks are cumulative over time, which

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- makes it difficult to match individuals if they acquire new marks or the marks change over time (Yoshizaki *et al.* 2009), the continuity and extension of our photographic identification work allowed us to register minor changes on the dorsal fins of individuals. The time between two primary sampling periods did not exceed 89 days, allowing for the identification of new marks in the dorsal fin (range 7–89 days; mean 31 days).
- 2. All individuals have equal probability of being captured within a sampling occasion. To ensure this assumption, attempts were made to photograph both sides of the dorsal fin of every dolphin during each encounter, and only 'excellent-quality' photographs were used in analyses. In addition, during dolphin encounters, explicit effort was made to photograph all the animals present, despite their markings, proximity to the boat or individual behaviour. Moreover, Pollock's robust design allows for heterogeneity of capture probabilities because the secondary sampling periods occur close together (Williams *et al.* 2002).
- 3. There is no behavioural response to the capture (i.e. no trap response). Boat-based photographic identification surveys did not induce significant behavioural changes or stress to the animals being studied. Moreover, the studied bottlenose dolphins are well habituated to human presence (marine traffic, aquaculture and fishing activities).
- 4. All individuals have equal probability of survival. To ensure this assumption, only adult bottlenose 222 dolphins were included in mark-recapture analyses. The presence of transient individuals is 223 commonly reported in cetacean studies based on photographic identification data (Silva *et al.* 2009; 224 Speakman et al. 2010). Ignoring the presence of transients can produce negatively biased survival 225 estimates because transients do not return to the study area (Hines et al. 2003). Program U-Care 226 (Choquet et al. 2005) was used to test and confirm the presence of transient individuals. The data 227 were adjusted for transience following an ad hoc approach (Hines et al. 2003) by relying on 228 individuals captured in more than one secondary period to provide direct estimates of survival rate 229 for residents. The ad hoc approach yields unbiased estimated pertaining to residents (Pradel et al. 230 231 1997; Hines et al. 2003).
- 5. The sampling interval for a particular secondary sample is instantaneous. To ensure this assumption, secondary periods were completed within the shortest period of time possible.
 - 6. The population is closed within primary periods. To ensure this assumption, primary periods were structured as seasons of the year rather than years. Moreover, because bottlenose dolphins are long-lived animals and the sampling period in the present study was short, demographic closure can be assumed. Furthermore, the CloseTest program (Stanley and Burnham 1999) was used to investigate population closure. Closure tests indicated population closure during all primary seasons (Stanley and Burnham closure test, χ² = 15.29, d.f. = 12, P = 0.23; Otis closure test, z-value = 1.91, P = 0.97).

7. Captures are independent between individuals. This assumption may have been violated, which is a common characteristic of dolphin mark—recapture data, because most bottlenose dolphin populations show non-random social preferences (Connor *et al.* 2000; Díaz López and Shirai 2008; Nicholson *et al.* 2012). This potential violation may cause an extra binomial variation, which is unlikely to cause a bias in the estimates obtained in the present study; however, standard errors are likely to be underestimated to some extent (Williams *et al.* 2002).

Modelling procedures and model selection

Mark–recapture analysis was conducted using the MARK version 8.1 (White and Burnham 1999). Data were analysed by Pollock's robust design model (Pollock 1982; Kendall *et al.* 1997). Closed captures and parameters were adjusted within the parameter index matrix (PIM) available in MARK. Estimated parameters within sampling periods included the abundance of distinctly marked adult individuals in the study area (\hat{N}), the probability of first capture (p) and the probability of recapture (p). Because capture should not affect recapture when using photographic identification methods adequately (Würsig and Jefferson 1990), robust models with a behavioural response were not fitted to the data. Therefore, p was set to equal p0 in all models. Estimated parameters between sampling periods included the probability of apparent survival (p0) and two temporary emigration parameters (p1 and p2 is defined as the probability that a bottlenose dolphin survives and stays in the study area scaled on a seasonal basis, p3 is defined as the probability of an individual being a temporary emigrant if the individual was absent in the previous sampling period and p3 is defined as the probability of an individual being a temporary emigrant if the individual being a temporary emigrant if the individual was present in the previous sampling period (Kendall *et al.* 1997).

A combination of different robust models, where parameters were either constant or were allowed to vary with time, were fitted for different temporary emigration patterns to look for a more parsimonious model. The models were no movement ($\gamma'' = 0$, $\gamma' = 1$), no temporary emigration ($\gamma'' = \gamma' = 0$), random emigration ($\gamma'' = \gamma'$) or Markovian emigration ($\gamma' \neq \gamma''$), as described in Kendall *et al.* (1997). A 'no movement' model assumes that unobservable individual bottlenose dolphins remain unobservable and that observable individuals always remain observable over all sampling occasions. No temporary emigration assumes that there is no temporary emigration at all. The random emigration model assumes that an identified bottlenose dolphin emigrates out of the study area independent of whether or not it was present in the study area in the previous sampling period. The Markovian emigration model permits unequal emigration and immigration rates across sampling periods, assuming that bottlenose dolphins return to the study area based on a time-dependent function (Pine *et al.* 2003). When models contained time-varying survival, constraints were placed (i.e. $\gamma''_k = \gamma''_{k-1}$, $\gamma'_k = \gamma'_{k-1}$), so that all parameters could be identified (Kendall *et al.* 1997). Capture probability was modelled as time varying over primary periods because environmental conditions were not constant over the duration of the study.

Furthermore, capture probability was modelled as either constant within primary periods (p = c(t, .)) or varying by secondary periods within primary periods (p = c(t)). Heterogeneity in capture probabilities was fitted to the data using mixture models with two mixtures of capture probability (Pledger 2000) only in models with no emigration because full-likelihood estimators have not yet been developed for temporary emigration models (Kendall *et al.* 1997).

There is no goodness-of-fit test for robust design models in MARK (White and Burnham 1999), so the overall model fit could not be evaluated and the models were not adjusted for overdispersion. The best fitting model was selected based on the lowest Akaike's information criterion corrected for small sample size (AICc; Burnham and Anderson 2004. Likelihood ratio tests (LRTs) were used to test for significant differences between nested models.

Total population size

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- Abundance estimates from the robust design models are based solely on the number of distinctly marked adult individuals ('well-marked' and 'marked' individuals). To obtain the total population size, $\hat{N}t$, the estimated abundance of distinctly marked adult individuals (Nm) was divided by the estimated proportion of distinctly marked adult individuals ($\hat{\theta}$) for each primary period (Wilson *et al.* 1999). To calculate $\hat{\theta}$, the number of distinctly marked adult individuals was divided by the total number of adult individuals observed in each group (including 'poorly marked' and 'unmarked' adults), averaged over all encounters during each season of the year:
- $293 \qquad \hat{N}t = \frac{Nm}{\hat{\theta}}$
- 294 For this calculation, we selected only encounters in which all members of the group were photographed.
- The s.e. and log-normal 95% confidence intervals (CI) of the total population size ($\hat{N}t$) were derived
- using the delta method (Williams *et al.* 2002).
 - Results
- 299 Survey effort, group size and datasets
- In all, 170 daily boat-based surveys were completed from March 2014 to June 2016 in the study area
- 301 (Table 1), with 25 months spent in the field, totalling 517 h and 4285 km.
- Overall, 386 groups of common bottlenose dolphins (*Tursiops truncatus*) were encountered in 157
- boat-based surveys (92% of total days at sea) and 309 groups were sampled and photographed (80% of
- the total number of groups observed). Most encounters (99.7%) were recorded inside the Ría de Arousa
- (Fig. 1). Group size ranged from 1 to 64 individuals (mean 13.0 ± 0.6 dolphins; median 10 dolphins).

Group composition showed that 87.7% of the observed bottlenose dolphins were considered adults; thus, the remaining 12.3% were categorised as dependent calves (11% immature and 1.3% newborn dolphins). Calves were present in 66% of the groups observed. Group size was positively correlated with the presence of dependent calves in the group (Spearman $\rho = 0.64$, P < 0.001). Likewise, the number of individuals in the group was significantly higher in the presence of dependent calves (median with and without calves 13 ν . 3 respectively; Mann–Whitney, P < 0.001).

312 Relative frequency of occurrence

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- The mean ER of groups of bottlenose dolphins in the study area was 1.77. The ER did not exhibit any differences between the nine primary sampling periods (Kruskal–Wallis, P > 0.05). Similarly, seasonal fluctuations in ER were not observed (when pooled by the four seasons of the year; Kruskal–Wallis, P > 0.05).
- Photographic identification data
- The photographic identification catalogue used in the analysis contained 190 distinctly marked adult bottlenose dolphins. Of these, 57 were documented as female (30%), 40 were documented as male (21%) and 93 (49%) were of unknown sex. The proportion of distinctly marked adult bottlenose dolphins within each primary period ranged between 0.68 and 0.92 (mean 0.77 \pm 0.01), exerting a moderate effect on the total abundance estimate. The number of encounters with identified individual bottlenose dolphins ranged from 1 to 101 (mean 16 ± 2) across the duration of the study. The number of primary sampling periods an identified individual bottlenose dolphin was photographed ranged from 1 to 9 (mean 3.6 ± 0.2). The number of encounters fluctuated across secondary sampling periods from 1 to 21 (mean 6.0 ± 0.4). Overall, 134 bottlenose dolphins (71% of the total catalogue) were identified in more than a single primary sampling period. Of these dolphins, 22 (4 females, 18 males) were identified during all the 9 primary sampling periods and in more than 75% of the secondary sampling periods. Conversely, 49 individuals (26% of the total catalogue) were only seen during a single secondary sampling period. All the individuals sighted during two or more secondary sampling seasons (141 dolphins) were only encountered inside the Ría de Arousa (a 240-km² area). During the study, only two groups of bottlenose dolphins were encountered outside the Ría de Arousa and included individuals that have never been recaptured (three identified individuals).

Robust design model selection

The best-fitting model, determined by the lowest AICc value, showed a constant apparent survival rate (rather than varying with time), seasonal Markovian temporary emigration (with time variation in emigration parameters γ'' and γ') and a different capture probability for each primary and secondary sampling occasion (Table 2). The LRT rejected the models with no movement, no emigration, random emigration, mixture proportion, Markovian emigration with variable survival rate and Markovian

- emigration with constant probability of capture in favour of the first model with a Markovian emigration
- process and constant apparent survival rate (Chi-Square, P < 0.001).
- 342 Abundance estimation
- For the best-fitting model, the estimated seasonal abundance of Nm varied between a minimum of
- 344 46 (95% CI 45.2–54.6) in spring 2015 and a maximum of 122 (95% CI 113.1–140.7) in winter 2015.
- 345 The $\hat{N}t$ ranged from 56 (95% CI 55.2–66.4) in autumn 2014 to 144 (95% CI 133.1–165.6) in winter
- 2015 (Table 3). Bottlenose dolphin abundance estimates were not significantly related to the ER
- (Spearman ρ , P > 0.05). Seasonal changes in abundance were most evident (+155%) between autumn
- 348 2014 (56 dolphins) and winter 2015 (144 dolphins) and between winter 2015 and spring 2015 (–60%).
- 349 Survival rates, temporal emigration patterns and capture probabilities
- 350 The model that best fitted the data gave a constant apparent survival rate of 1.0 ± 0.0 . Temporary
- emigration rates were higher from summer to autumn and lower from autumn to winter. The probability
- of being a temporary emigrant if the individual bottlenose dolphin was absent in the previous season
- 353 (γ') was high, with a mean value of 0.68 \pm 0.12. Conversely, the probability of being a temporary
- emigrant if the individual bottlenose dolphin was present in the previous season (γ'') was low, with a
- mean of 0.23 ± 0.07 (Table 4). Mean capture probabilities among seasons were moderate (0.65 ± 0.03) ,
- with the highest obtained in spring 2015 (0.80 \pm 0.02) and the lowest during spring 2016 (0.56 \pm 0.09).
- Temporal emigration rates (γ' and γ'') and capture probabilities did not show significant differences
- between seasons (Kruskal–Wallis, P > 0.05).

Discussion

- This study presents the first robust estimates of abundance and demographic parameters of resident
- 361 common bottlenose dolphins (T. truncatus) in a highly affected coastal ecosystem along the north-
- eastern Atlantic. Further, these results provide baseline information for future comparisons with other
- populations of similar characteristics under the pressure of human activities (i.e. marine traffic, fisheries
- and aquaculture), which may become of increasing importance as anthropogenic activities affect coastal
- 365 dolphin populations.
- Bottlenose dolphins are present year-round and with a high degree of occurrence inside the Ría de
- Arousa, an area highly affected by human activities, but also a highly productive estuarine system. This
- area not only produces an important amount of commercially valuable shellfish as a result of the
- aquaculture industry (Rodríguez *et al.* 2011), but the epifaunal community associated with the shellfish
- 370 production also supports the substantial production of fish and megabenthos compared with other
- coastal and estuarine areas (Chesney and Iglesias 1979). Similar abundance estimates in terms of the
- number of individuals present have been obtained in other studies, performed using mark-recapture
- methods rather than the robust design model, of north-east Atlantic bottlenose dolphin populations

living in rich coastal environments, such as Moray Firth, Scotland (Wilson *et al.* 1999) and the Shannon Estuary, Ireland (Berrow *et al.* 2012).

This study reports seasonal fluctuations in abundance as observed in other bottlenose dolphin populations (Smith *et al.* 2013; Sprogis *et al.* 2016). Although there may be different factors playing a key role in bottlenose dolphin distribution to some extent, the observed changes in abundance and emigration rates most likely reflect seasonal fluctuations in the abundance of prey species in this area. Bottlenose dolphins in Galicia eat a wide range of demersal fish species (Santos *et al.* 2007). These fish species are a resident component of the Ría de Arousa (Fariña *et al.* 1997) and a possible explanation for the estimates of bottlenose dolphin abundance and observed large group size compared with other coastal populations (Bearzi *et al.* 1997; Díaz López *et al.* 2013; Santostasi *et al.* 2016). Thus, the winter season, with the highest abundance and lowest emigration rates of bottlenose dolphins observed in this study, is characterised by a peak in numbers of demersal fish species inside the Ría de Arousa (Chesney and Iglesias 1979). Moreover, the derived return rate $(1 - \gamma')$ of temporary emigrants (Sprogis *et al.* 2016) indicated that bottlenose dolphins had a high probability of returning to the Ría de Arousa from autumn to winter.

The estimated apparent survival rate is high and constant, suggesting no mortality and no permanent emigration of individuals during the duration of the study. These results are common for long-lived species with slow growth rates and low fecundity, and have been reported in other bottlenose dolphin populations (Nicholson *et al.* 2012; Sprogis *et al.* 2016).

The results of the present study show seasonal fluctuations in the temporary emigration rates. Temporary emigration rates for dolphins that were absent in the previous period were higher (0.38–0.89) than those for dolphins that were present (0.08–0.37), suggesting different levels of site fidelity. Some individuals (22 males, 4 females) showed a strong preference for the study area (being present in all primary periods), so there is a core of resident bottlenose dolphins in the Ría de Arousa with some other dolphins coming in and out of the study area for different periods of time. The age and sex of each individual, as well as its ecological and social preferences, could explain the differences in the residence patterns observed (Bearzi et al. 1997). In these waters, resident males may have a smaller home range than females, showing a stronger site fidelity to the Ría de Arousa. Different reasons could help explain the observed differences in site fidelity, such as different tolerances to human disturbance or different prey preferences. The latter is supported by a study about the diet of bottlenose dolphins in the region that indicated differences in diet between males and females (Santos et al. 2007). In contrast with other areas where females stay in sheltered waters for protection from predation, showing strong site fidelity (Nicholson et al. 2012; Smith et al. 2013), the absence of natural predators in the present study area may not constrain females to a small home range. Moreover, area defence by individuals or social

groups could also help explain the observed differences in site fidelity and temporal occurrence rates observed in the present compared with other studies (Díaz López 2012).

Previous studies of wild populations of dolphins have documented avoidance of highly affected ecosystems where humans are present (Dawson and Slooten 1993; Bejder *et al.* 2006; Bearzi *et al.* 2009, 2008a, 2008b; Rako *et al.* 2013), although others have reported continued use of valuable habitat areas despite high levels of human disturbance (Ingram and Rogan 2002; Bearzi *et al.* 2008b; Díaz López 2012). In highly affected and highly productive coastal ecosystems, like the Ría de Arousa, where human impact levels are consistently high primarily due to fisheries and aquaculture activities, some bottlenose dolphins may have become habituated to these predictable disturbance levels and continued to use this affected, but rich, habitat. Indeed, previous studies in the Ría de Arousa reported a relationship between the occurrence of bottlenose dolphins and mussel aquaculture zones as a result of higher densities of higher-quality prey for dolphins than in areas outside the mussel farm zones (Díaz López and Methion 2017).

The presence of bottlenose dolphins in the Ría de Arousa should not be assumed to mean that human disturbance has no effect on these bottlenose dolphins. The effects of human activities on bottlenose dolphins could differ between individuals because of individual variability in site fidelity. Future research that compares home range, social structure and reproductive success of bottlenose dolphins would help reveal individual-level effects of human disturbance, should they exist.

Conflicts of interest

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The authors declare that they have no conflicts of interest.

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Table 1. Annual observation effort, robust design periods, bottlenose dolphin encounters, encounter ratio and the number of bottlenose dolphins identified included in the mark–recapture analysis

The encounter ratio (ER) was calculated by dividing the total number of encounters by the total number of hours spent searching for dolphins

Year	Robu	st design	Observation effort			t	Number of	ER	Number of
	Number of primary periods	Number of secondary periods	Months	Days	Hours	Kilometres	group encounters		bottlenose dolphins identified
2014	3	8	9	67	217	1625	139	1.47	119
2015	4	9	10	63	191	1646	151	1.88	137
2016	2	5	6	40	109	1014	96	2.20	129
Total	9	22	25	170	517	4285	386	1.77	190

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Table 2. Capture–recapture models fitted to the capture histories of bottlenose dolphins to estimate parameters for population size (\hat{N}), apparent survival (ϕ), emigration probabilities (γ'' , γ') and capture probability (p)

The notation '(.)' indicates that a given parameter was kept constant and '(t)' indicates that a given parameter was allowed to vary with time. Emigration pattern notations follow Kendall *et al.* (1997). c, recapture probability; γ' , probability of an individual being a temporary emigrant if the individual was absent in the previous sampling period; γ'' , probability of an individual being a temporary emigrant if the individual was present in the previous sampling period; pi, mixture proportion; AICc, Akaike's information criterion corrected for small sample size

Rank	Model	Emigration pattern	AICc	ΔAICc	Model likelihood	AICc weight	Parameters	Deviance
1	$\phi(.), \gamma'(t) \neq \gamma''(t), p(t) = c(t)$	Markovian	-1447.2	0.00	1.0000	0.999	47	1524.0
2	$\phi(t), \gamma'(t) \neq \gamma''(t), p(t) = c(t)$	Markovian	-1432.6	14.6	0.0007	0.001	52	1527.6
3	$\phi(.), \gamma'(t) \neq \gamma''(t), p(t,.) = c(t,.)$	Markovian	-1378.1	69.1	0.0000	0.000	34	1621.2
4	$\phi(t), \gamma'(t) \neq \gamma''(t), p(t,.) = c(t,.)$	Markovian	-1361.3	85.8	0.0000	0.000	38	1629.4
5	$\phi(t), \gamma'(t) = \gamma''(t), p(t) = c(t)$	Random	-1328.9	118.3	0.0000	0.000	46	1644.5
6	$\phi(.), \gamma'(t) = \gamma''(t), p(t) = c(t)$	Random	-1321.3	125.9	0.0000	0.000	40	1665.1
7	$\phi(t), \gamma' = \gamma'' = 0, pi(t), p(t)$	No emigration	-1312.7	134.4	0.0000	0.000	38	1678.0
8	$\phi(t), \gamma' = \gamma'' = 0, pi(.), p(t)$	No emigration	-1293.0	154.2	0.0000	0.000	36	1702.0
9	$\phi(t), \gamma'(t) = \gamma''(t), p(t,.) = c(t,.)$	Random	-1259.9	187.3	0.0000	0.000	33	1741.5
10	$\phi(.), \gamma'(t) = \gamma''(t), p(t,.) = c(t,.)$	Random	-1252.8	194.4	0.0000	0.000	27	1761.3
11	$\phi(t), \gamma' = \gamma'' = 0, p(t) = c(t)$	No emigration	-1112.9	334.3	0.0000	0.000	39	1875.6

12	$\phi(t), \gamma' = 1, \gamma'' = 0, p(t) = c(t)$	No movement	-1112.9	334.3	0.0000	0.000	39	1875.6
13	$\phi(.), \gamma' = 1, \gamma'' = 0, p(t) = c(t)$	No movement	-1092.7	354.5	0.0000	0.000	32	1910.8
14	$\phi(.), \gamma' = \gamma'' = 0, p(t) = c(t)$	No emigration	-1092.7	354.5	0.0000	0.000	32	1910.8
15	$\phi(t), \gamma' = 1, \gamma'' = 0, p(t,.) = c(t,.)$	No movement	-1069.2	377.2	0.0000	0.000	26	1947.0
16	$\phi(t), \gamma' = \gamma'' = 0, p(t,.) = c(t,.)$	No emigration	-1069.2	377.9	0.0000	0.000	26	1947.0
17	$\phi(.), \gamma' = 1, \gamma'' = 0, p(t,.) = c(t,.)$	No movement	-1048.9	398.3	0.0000	0.000	19	1981.9
18	$\phi(.), \gamma' = \gamma'' = 0, p(t,.) = c(t,.)$	No emigration	-1048.9	398.3	0.0000	0.000	19	1981.9

Table 3. Seasonal abundance estimates of bottlenose dolphins in the study area

 \hat{N} , estimation of the marked population; $\hat{\theta}$, proportion of distinctly marked adult individuals; $\hat{N}t$, total population size; CI, confidence interval

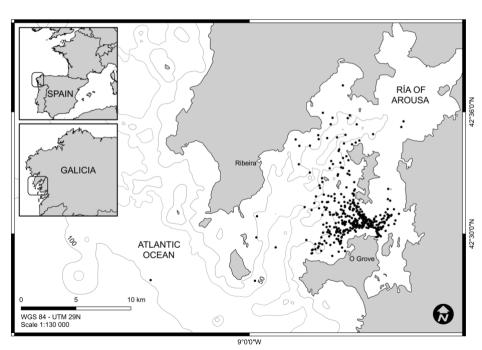
Year	Season	Number of dolphins identified	\hat{N}	s.e.	$\hat{ heta}$	Ñt	95% CI
2014	Spring	73	76	2.8	0.68	111	107–125
	Summer	100	85	3.0	0.69	123	118-138
	Autumn	37	50	1.8	0.89	56	55–66
2015	Winter	115	122	6.7	0.85	144	133–166
	Spring	46	46	1.8	0.81	57	56–67
	Summer	82	68	1.2	0.88	77	76–84
	Autumn	40	61	3.5	0.92	66	62–78
2016	Winter	84	87	3.3	0.75	116	110-130
	Spring	114	110	4.0	0.79	139	133-153

Table 4. Mean seasonal temporary emigration rates for the best fitting Markovian model Data are the mean \pm s.e. γ' , probability of an individual being a temporary emigrant if the individual was absent in the previous sampling period; γ'' , probability of an individual being a temporary

emigrant if the individual was present in the previous sampling period

Season	Temporary emigration rates				
	γ'	γ"			
Winter-spring	0.73 ± 0.27	0.34 ± 0.26			
Spring-summer	0.75 ± 0.00	0.14 ± 0.08			
Summer-autumn	0.89 ± 0.04	0.37 ± 0.08			
Autumn-winter	0.38 ± 0.28	0.08 ± 0.04			
Overall	0.68 ± 0.12	0.23 ± 0.07			

Fig. 1. Map of the study area (Ría de Arousa and surrounding waters, north-west Spain) including the 50 and 100 isobaths. Bottlenose dolphin encounters are indicated by filled circles.



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